

Attribute Implications and Other Data Dependencies

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INVESTMENTS IN EDUCATION DEVELOPMENT

Introducing attribute implications

Attribute implications (AIs) are expressions describing particular dependencies among attributes in relational data.

Examples:

$\{\text{prime}, > 2\} \Rightarrow \{\text{odd}\}$, $\{\text{flight No.}\} \Rightarrow \{\text{depart. time, arriv. time}\}$.

AIs used in

- **formal concept analysis**
 - interpreted in formal contexts (tables with yes/no-attributes)
 - knowledge extraction
- **relational databases** (called functional dependencies)
 - interpreted in DB relations (tables with general attributes)
 - data redundancy, normalization, DB design
 - knowledge extraction
- **data mining** (called association rules)
 - interpreted in formal contexts (tables with yes/no-attributes)
 - validity modified by confidence, support (interestingness)
 - knowledge extraction

Introducing attribute implications

basic literature:

- formal concept analysis
 - Ganter, Wille: Formal Concept Analysis. Mathematical Foundations. Springer, 1999.
 - Carpineto C., Romano G.: Concept Data Analysis. Wiley, 2004.
- relational databases
 - Any textbook on databases.
 - Maier D.: The Theory of Relational Databases. Computer Science Press, 1983.
- data mining (association rules)
 - Any textbook on Data Mining.
 - Zhang , Zhang: Association Rule Mining. Springer, 2002.

Introducing attribute implications

Als are interpreted in tables (formal contexts) $\mathcal{T} = \langle X, Y, I \rangle$ such as

table \mathcal{T}

	y_1	y_2	y_3	y_4
x_1	×	×	×	×
x_2	×		×	×
x_3		×	×	×
x_4		×	×	×
x_5	×		×	

$X = \{x_1, \dots\}$... **objects** (rows)

$Y = \{y_1, \dots\}$... **attributes** (columns)

× ... **incidence** (object has attribute)

attribute implication ... $A \Rightarrow B$ where $A, B \subseteq Y$ (sets of attributes)

$A \Rightarrow B$ is true in table \mathcal{T} means

for each object x :

IF x has all attributes from A THEN x has all attr. from B

Example:

$\{y_1\} \Rightarrow \{y_3\}$, $\{y_2, y_3\} \Rightarrow \{y_4\}$ are true in \mathcal{T} ,
 $\{y_1\} \Rightarrow \{y_2\}$ is not (x_2 as a counterexample)

Als – basic notions

Definition (attribute implication)

Let Y be a non-empty set (of attributes). An attribute implication over Y is an expression

$$A \Rightarrow B$$

where $A \subseteq Y$ and $B \subseteq Y$ (A and B are sets of attributes).

Example

- Let $Y = \{y_1, y_2, y_3, y_4\}$. Then $\{y_2, y_3\} \Rightarrow \{y_1, y_4\}$, $\{y_2, y_3\} \Rightarrow \{y_1, y_2, y_3\}$, $\emptyset \Rightarrow \{y_1, y_2\}$, $\{y_2, y_4\} \Rightarrow \emptyset$ are Als over Y .
- Let $Y = \{\text{watches-TV, eats-unhealthy-food, runs-regularly, normal-blood-pressure, high-blood-pressure}\}$. Then $\{\text{watches-TV, eats-unhealthy-food}\} \Rightarrow \{\text{high-blood-pressure}\}$, $\{\text{runs-regularly}\} \Rightarrow \{\text{normal-blood-pressure}\}$ are attribute implications over Y .

Als – validity

- Basic semantic structures in which we evaluate attribute implications are rows of tables (of formal contexts).

- Table rows can be regarded as sets of attributes. In table

	y_1	y_2	y_3	y_4
x_1	×	×	×	×
x_2	×			×
x_3				

, rows

corresponding to x_1 , x_2 , and x_3 can be regarded as sets $M_1 = \{y_1, y_2, y_3, y_4\}$, $M_2 = \{y_1, y_4\}$, and $M_3 = \emptyset$.

- Therefore, we need to define a notion of a validity of an AI in a set M of attributes.

Definition (validity of attribute implication)

An attribute implication $A \Rightarrow B$ over Y is true (valid) in a set $M \subseteq Y$ iff
 $A \subseteq M$ implies $B \subseteq M$.

- We write

$$\|A \Rightarrow B\|_M = \begin{cases} 1 & \text{if } A \Rightarrow B \text{ is true in } M, \\ 0 & \text{if } A \Rightarrow B \text{ is not true in } M. \end{cases}$$

- Let M be a set of attributes of some object x . $\|A \Rightarrow B\|_M = 1$ says “if x has all attributes from A then x has all attributes from B ”, because “if x has all attributes from C ” is equivalent to $C \subseteq M$.

Example

- Let $Y = \{y_1, y_2, y_3, y_4\}$.

$A \Rightarrow B$	M	$\ A \Rightarrow B\ _M$	why
$\{y_2, y_3\} \Rightarrow \{y_1\}$	$\{y_2\}$	1	$A \not\subseteq M$
$\{y_2, y_3\} \Rightarrow \{y_1\}$	$\{y_1, y_2\}$	1	$A \not\subseteq M$
$\{y_2, y_3\} \Rightarrow \{y_1\}$	$\{y_1, y_2, y_3\}$	1	$A \subseteq M$ and $B \subseteq M$
$\{y_2, y_3\} \Rightarrow \{y_1\}$	$\{y_2, y_3, y_4\}$	0	$A \subseteq M$ but $B \not\subseteq M$
$\{y_2, y_3\} \Rightarrow \{y_1\}$	\emptyset	1	$A \not\subseteq \emptyset$
$\emptyset \Rightarrow \{y_1\}$	$\{y_1, y_4\}$	1	$\emptyset \subseteq M$ and $B \subseteq M$.
$\emptyset \Rightarrow \{y_1\}$	$\{y_3, y_4\}$	0	$\emptyset \subseteq M$ but $B \not\subseteq M$.
$\{y_2, y_3\} \Rightarrow \emptyset$	any M	1	$\emptyset \subseteq M$

- extend validity of $A \Rightarrow B$ to collections \mathcal{M} of M 's (collections of subsets of attributes), i.e. define validity of $A \Rightarrow B$ in $\mathcal{M} \subseteq 2^Y$.

Definition

Let $\mathcal{M} \subseteq 2^Y$ (elements of \mathcal{M} are subsets of attributes). An attribute implication $A \Rightarrow B$ over Y is true (valid) in \mathcal{M} if $A \Rightarrow B$ is true in each $M \in \mathcal{M}$.

- Again,

$$\|A \Rightarrow B\|_{\mathcal{M}} = \begin{cases} 1 & \text{if } A \Rightarrow B \text{ is true in } \mathcal{M}, \\ 0 & \text{if } A \Rightarrow B \text{ is not true in } \mathcal{M}. \end{cases}$$

Note that a formal context $\langle X, Y, I \rangle$ is a triplet where X and Y are non-empty sets (of objects and attributes) and $I \subseteq X \times Y$ is a binary relation interpreted as: $\langle x, y \rangle \in I$ if and only if object x has attribute y .

Definition (validity of attribute implications in formal contexts)

An attribute implication $A \Rightarrow B$ over Y is true in a table (formal context) $\langle X, Y, I \rangle$ iff $A \Rightarrow B$ is true in

$$\mathcal{M} = \{\{x\}^\uparrow \mid x \in X\}.$$

- We write $\|A \Rightarrow B\|_{\langle X, Y, I \rangle} = 1$ if $A \Rightarrow B$ is true in $\langle X, Y, I \rangle$.
- Note that, $\{x\}^\uparrow$ is the set of attributes of x (row corresponding to x). Hence, $\mathcal{M} = \{\{x\}^\uparrow \mid x \in X\}$ is the collection whose members are just sets of attributes of objects (i.e., rows) of $\langle X, Y, I \rangle$. Therefore, $\|A \Rightarrow B\|_{\langle X, Y, I \rangle} = 1$ iff $A \Rightarrow B$ is true in each row of $\langle X, Y, I \rangle$ iff for each $x \in X$:
if x has all attributes from A then x has all attributes from B .

Example

Consider attributes normal blood pressure (nbp), high blood pressure (hbp), watches TV (TV), eats unhealthy food (uf), runs regularly (r), and table

I	nbp	hbp	TV	uf	r
a	×				×
b	×			×	×
c		×	×	×	
d		×		×	
e	×				

Then

$A \Rightarrow B$	$\ A \Rightarrow B\ _{\langle X, Y, I \rangle}$	why
$\{r\} \Rightarrow \{nbp\}$	1	
$\{TV, uf\} \Rightarrow \{hbp\}$	1	
$\{TV\} \Rightarrow \{hbp\}$	1	
$\{uf\} \Rightarrow \{hbp\}$	0	b counterexample
$\{nbp\} \Rightarrow \{r\}$	0	e counterexample
$\{nbp, hbp\} \Rightarrow \{r, TV\}$	1	A never satisfied
$\{uf, r\} \Rightarrow \{r\}$	1	

Als – theory, models, semantic consequence

- Previous example: $\{TV, uf\} \Rightarrow \{hbp\}$ intuitively follows from $\{TV\} \Rightarrow \{hbp\}$. Therefore, provided we establish validity of $\{TV\} \Rightarrow \{hbp\}$, $AI \{TV, uf\} \Rightarrow \{hbp\}$ is redundant.
Another example: $A \Rightarrow C$ follows from $A \Rightarrow B$ and $B \Rightarrow C$ (for any A, B, C).
- Need to capture intuitive notion of entailment of attribute implications. We use standard notions of a theory and model.
- Eventually, we want to have a small set T of Als which are valid in $\langle X, Y, I \rangle$ such that all other Als which are true in $\langle X, Y, I \rangle$ follow from T .

Definition (theory, model)

A theory (over Y) is any set T of attribute implications (over Y).

A model of a theory T is any $M \subseteq Y$ such that every $A \Rightarrow B$ from T is true in M .

- $\text{Mod}(T)$ denotes all models of a theory T , i.e.

$$\text{Mod}(T) = \{M \subseteq Y \mid \text{for each } A \Rightarrow B \in T : A \Rightarrow B \text{ is true in } M\}.$$

- Intuitively, a theory is some “important” set of attribute implications. For instance, T may contain AIs established to be true in data (extracted from data).
- Intuitively, a model of T is (a set of attributes of some) object which satisfies every AI from T .
- Notions of theory and model do not depend on some particular $\langle X, Y, I \rangle$.

Example (theories over $\{y_1, y_2, y_3\}$)

- $T_1 = \{\{y_3\} \Rightarrow \{y_1, y_2\}, \{y_1, y_3\} \Rightarrow \{y_2\}\}$.
- $T_2 = \{\{y_3\} \Rightarrow \{y_1, y_2\}\}$.
- $T_3 = \{\{y_1, y_3\} \Rightarrow \{y_2\}\}$.
- $T_4 = \{\{y_1\} \Rightarrow \{y_3\}, \{y_3\} \Rightarrow \{y_1\}, \{y_2\} \Rightarrow \{y_2\}\}$.
- $T_5 = \emptyset$.
- $T_6 = \{\emptyset \Rightarrow \{y_1\}, \emptyset \Rightarrow \{y_3\}\}$.
- $T_7 = \{\{y_1\} \Rightarrow \emptyset, \{y_2\} \Rightarrow \emptyset, \{y_3\} \Rightarrow \emptyset\}$.
- $T_8 = \{\{y_1\} \Rightarrow \{y_2\}, \{y_2\} \Rightarrow \{y_3\}, \{y_3\} \Rightarrow \{y_1\}\}$.

Example (models of theories over $\{y_1, y_2, y_3\}$)

Determine $\text{Mod}(T)$ of the following theories over $\{y_1, y_2, y_3\}$.

- $T_1 = \{\{y_3\} \Rightarrow \{y_1, y_2\}, \{y_1, y_3\} \Rightarrow \{y_2\}\}$.
 $\text{Mod}(T_1) = \{\emptyset, \{y_1\}, \{y_2\}, \{y_1, y_2\}, \{y_1, y_2, y_3\}\}$,
- $T_2 = \{\{y_3\} \Rightarrow \{y_1, y_2\}\}$.
 $\text{Mod}(T_2) = \{\emptyset, \{y_1\}, \{y_2\}, \{y_1, y_2\}, \{y_1, y_2, y_3\}\}$ (note: $T_2 \subset T_1$ but $\text{Mod}(T_1) = \text{Mod}(T_2)$),
- $T_3 = \{\{y_1, y_3\} \Rightarrow \{y_2\}\}$.
 $\text{Mod}(T_3) = \{\emptyset, \{y_1\}, \{y_2\}, \{y_3\}, \{y_1, y_2\}, \{y_2, y_3\}, \{y_1, y_2, y_3\}\}$ (note: $T_3 \subset T_1$, $\text{Mod}(T_1) \subset \text{Mod}(T_2)$),
- $T_4 = \{\{y_1\} \Rightarrow \{y_3\}, \{y_3\} \Rightarrow \{y_1\}, \{y_2\} \Rightarrow \{y_2\}\}$.
 $\text{Mod}(T_4) = \{\emptyset, \{y_2\}, \{y_1, y_3\}, \{y_1, y_2, y_3\}\}$
- $T_5 = \emptyset$. $\text{Mod}(T_5) = 2^{\{y_1, y_2, y_3\}}$. Why: $M \in \text{Mod}(T)$ iff for each $A \Rightarrow B$: if $A \Rightarrow B \in T$ then $\|A \Rightarrow B\|_M = 1$.
- $T_6 = \{\emptyset \Rightarrow \{y_1\}, \emptyset \Rightarrow \{y_3\}\}$. $\text{Mod}(T_6) = \{\{y_1, y_3\}, \{y_1, y_2, y_3\}\}$.
- $T_7 = \{\{y_1\} \Rightarrow \emptyset, \{y_2\} \Rightarrow \emptyset, \{y_3\} \Rightarrow \emptyset\}$. $\text{Mod}(T_7) = 2^{\{y_1, y_2, y_3\}}$.
- $T_8 = \{\{y_1\} \Rightarrow \{y_2\}, \{y_2\} \Rightarrow \{y_3\}, \{y_3\} \Rightarrow \{y_1\}\}$. $\text{Mod}(T_8) = \{\emptyset, \{y_1, y_2, y_3\}\}$.

Definition (semantic consequence)

An attribute implication $A \Rightarrow B$ follows semantically from a theory T , which is denoted by

$$T \models A \Rightarrow B,$$

iff $A \Rightarrow B$ is true in every model M of T ,

- Therefore, $T \models A \Rightarrow B$ iff for each $M \subseteq Y$: if $M \in \text{Mod}(T)$ then $\|A \Rightarrow B\|_M = 1$.
- Intuitively, $T \models A \Rightarrow B$ iff $A \Rightarrow B$ is true in every situation where every AI from T is true (replace “situation” by “model”).
- Terminology: $T \models A \Rightarrow B \dots A \Rightarrow B$ follows semantically from $T \dots A \Rightarrow B$ is semantically entailed by $T \dots A \Rightarrow B$ is a semantic consequence of T .

How to decide by definition whether $T \models A \Rightarrow B$?

1. Determine $\text{Mod}(T)$.
2. Check whether $A \Rightarrow B$ is true in every $M \in \text{Mod}(T)$; if yes then $T \models A \Rightarrow B$; if not then $T \not\models A \Rightarrow B$.

Later on, we will see how to efficiently check whether $T \models A \Rightarrow B$.

Example (semantic entailment)

Let $Y = \{y_1, y_2, y_3\}$. Determine whether $T \models A \Rightarrow B$.

- $T = \{\{y_3\} \Rightarrow \{y_1, y_2\}, \{y_1, y_3\} \Rightarrow \{y_2\}\}$, $A \Rightarrow B$ is $\{y_2, y_3\} \Rightarrow \{y_1\}$.
 1. $\text{Mod}(T) = \{\emptyset, \{y_1\}, \{y_2\}, \{y_1, y_2\}, \{y_1, y_2, y_3\}\}$.
 2. $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\emptyset} = 1$, $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\{y_1\}} = 1$, $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\{y_2\}} = 1$,
 $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\{y_1, y_2\}} = 1$, $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\{y_1, y_2, y_3\}} = 1$.
Therefore, $T \models A \Rightarrow B$.
- $T = \{\{y_3\} \Rightarrow \{y_1, y_2\}, \{y_1, y_3\} \Rightarrow \{y_2\}\}$, $A \Rightarrow B$ is $\{y_2\} \Rightarrow \{y_1\}$.
 1. $\text{Mod}(T) = \{\emptyset, \{y_1\}, \{y_2\}, \{y_1, y_2\}, \{y_1, y_2, y_3\}\}$.
 2. $\|\{y_2\} \Rightarrow \{y_1\}\|_{\emptyset} = 1$, $\|\{y_2\} \Rightarrow \{y_1\}\|_{\{y_1\}} = 1$, $\|\{y_2\} \Rightarrow \{y_1\}\|_{\{y_2\}} = 0$, we can stop.
Therefore, $T \not\models A \Rightarrow B$.

Mod(T) as a closure system

Definition (closure system)

A closure system in a set Y is any system \mathcal{S} of subsets of Y which contains Y and is closed under arbitrary intersections.

That is, $Y \in \mathcal{S}$ and $\bigcap \mathcal{R} \in \mathcal{S}$ for every $\mathcal{R} \subseteq \mathcal{S}$ (intersection of every subsystem \mathcal{R} of \mathcal{S} belongs to \mathcal{S}).

$\{\{a\}, \{a, b\}, \{a, d\}, \{a, b, c, d\}\}$ is a closure system in $\{a, b, c, d\}$ while $\{\{a, b\}, \{c, d\}, \{a, b, c, d\}\}$ is not. Why?

Definition (closure operator)

A closure operator in a set Y is any mapping $C : 2^Y \rightarrow 2^Y$ satisfying:

- (i) $A \subseteq C(A)$;
 - (ii) $A \subseteq B$ implies $C(A) \subseteq C(B)$;
 - (iii) $C(A) = C(C(A))$,
- for every $A, B \in 2^Y$.

There is a one-to-one relationship between closure systems and closure operators in Y .

(1) Given a closure operator C in Y , $\mathcal{S}_C = \{A \in 2^X \mid A = C(A)\} = \text{fix}(C)$ is a closure system in Y .

(2) Given a closure system in Y , putting

$$C_{\mathcal{S}}(A) = \bigcap \{B \in \mathcal{S} \mid A \subseteq B\}$$

for any $A \subseteq X$, $C_{\mathcal{S}}$ is a closure operator on Y . This is a one-to-one relationship, i.e. $C = C_{\mathcal{S}_C}$ and $\mathcal{S} = \mathcal{S}_{C_{\mathcal{S}}}$.

Observe: If \mathcal{S} is a closure system and C the corresponding closure operator in Y then for every $A \subseteq Y$, $C(A)$ is the least element from \mathcal{S} of which is a subset.

Recall: $\text{Mod}(T) = \{M \subseteq Y \mid \|A \Rightarrow B\|_M = 1 \text{ for every } A \Rightarrow B \in T\}$

Lemma

For a set T of attribute implications, $\text{Mod}(T)$ is a closure system in Y .

Proof.

First, $Y \in \text{Mod}(T)$ because Y is a model of any attribute implication.

Second, let $M_j \in \text{Mod}(T)$ ($j \in J$). For any $A \Rightarrow B \in T$, if $A \subseteq \bigcap_j M_j$ then for each $j \in J$: $A \subseteq M_j$, and so $B \subseteq M_j$ (since $M_j \in \text{Mod}(T)$, thus in particular $M_j \models A \Rightarrow B$), from which we have $B \subseteq \bigcap_j M_j$.

We showed that $\text{Mod}(T)$ contains Y and is closed under intersections, i.e. $\text{Mod}(T)$ is a closure system. □

Since $\text{Mod}(T)$ is a closure system, we can consider the corresponding closure operator $C_{\text{Mod}(T)}$ (i.e., the fixed points of $C_{\text{Mod}(T)}$ are just models of T). Therefore, for every $A \subseteq Y$ there exist the least model of $\text{Mod}(T)$ which contains A , namely, such least model is just $C_{\text{Mod}(T)}(A)$.

Theorem (testing entailment via least model)

For any $A \Rightarrow B$ and any T , we have

$$T \models A \Rightarrow B \quad \text{iff} \quad \|A \Rightarrow B\|_{C_{\text{Mod}(T)}(A)} = 1,$$

i.e., $A \Rightarrow B$ semantically follows from T iff $A \Rightarrow B$ is true in the least model $C_{\text{Mod}(T)}(A)$ of T which contains A .

Proof.

“ \Rightarrow ”: If $T \models A \Rightarrow B$ then, by definition, $A \Rightarrow B$ is true in every model of T . Therefore, in particular, $A \Rightarrow B$ is true in $C_{\text{Mod}(T)}(A)$.

“ \Leftarrow ”: Let $A \Rightarrow B$ be true in $C_{\text{Mod}(T)}(A)$. Since $A \subseteq C_{\text{Mod}(T)}(A)$, we have $B \subseteq C_{\text{Mod}(T)}(A)$. We need to check that $A \Rightarrow B$ is true in every model of T . Let thus $M \in \text{Mod}(T)$. If $A \not\subseteq M$ then, clearly, $A \Rightarrow B$ is true in M . If $A \subseteq M$ then, since M is a model of T containing A , we have $C_{\text{Mod}(T)}(A) \subseteq M$ (because $C_{\text{Mod}(T)}(A)$ is the least model of T containing A). Putting together with $B \subseteq C_{\text{Mod}(T)}(A)$, we get $B \subseteq M$, i.e. $A \Rightarrow B$ is true in M . □

Checking entailment via least model

- Previous theorem implies that we may test $T \models A \Rightarrow B$ by checking whether $A \Rightarrow B$ is true in a single particular model of T , namely in $\text{Mod}(T)(A)$. This is much better than going by definition \models (definition says: $T \models A \Rightarrow B$ iff $A \Rightarrow B$ is true in every model of T).
- How can we obtain $C_{\text{Mod}(T)}(A)$?

Definition

For $Z \subseteq Y$, T a set of implications, put

1. $Z^T = Z \cup \bigcup \{B \mid A \Rightarrow B \in T, A \subseteq Z\}$,
2. $Z^{T_0} = Z$,
3. $Z^{T_n} = (Z^{T_{n-1}})^T$ (for $n \geq 1$).

Define define operator $C : 2^Y \rightarrow 2^Y$ by

$$C(Z) = \bigcup_{n=0}^{\infty} Z^{T_n}$$

Theorem

Given T , C (defined on previous slide) is a closure operator in Y such that

$$C(Z) = C_{\text{Mod}(T)}(Z).$$

Proof.

First, check that C is a closure operator.

$Z = Z^{T_0}$ yields $Z \subseteq C(Z)$.

Evidently, $Z_1 \subseteq Z_2$ implies $Z_1^T \subseteq Z_2^T$ which implies $Z_1^{T_1} \subseteq Z_2^{T_1}$ which implies $Z_1^{T_2} \subseteq Z_2^{T_2}$ which implies $\dots Z_1^{T_n} \subseteq Z_2^{T_n}$ for any n . That is, $Z_1 \subseteq Z_2$ implies

$$C(Z_1) = \bigcup_{n=0}^{\infty} Z_1^{T_n} \subseteq \bigcup_{n=0}^{\infty} Z_2^{T_n} = C(Z_2).$$

$C(Z) = C(C(Z))$: Clearly,

$$Z^{T_0} \subseteq Z^{T_1} \subseteq \dots Z^{T_n} \subseteq \dots$$

Since Y is finite, the above sequence terminates after a finite number n_0 of steps, i.e. there is n_0 such that

$$C(Z) = \bigcup_{n=0}^{\infty} Z^{T_n} = Z^{T_{n_0}}.$$

This means $(Z^{T_{n_0}})^T = Z^{T_{n_0}} = C(Z)$ which gives $C(Z) = C(C(Z))$. □

cntd.

Next, we check $C(Z) = C_{\text{Mod}(T)}(Z)$.

1. $C(Z)$ is a model of T containing Z :

Above, we checked that $C(Z)$ contains Z . Take any $A \Rightarrow B \in T$ and verify that $A \Rightarrow B$ is valid in $C(Z)$ (i.e., $C(Z)$ is a model of $A \Rightarrow B$). Let $A \subseteq C(Z)$. We need to check $B \subseteq C(Z)$. $A \subseteq C(Z)$ means that for some n , $A \subseteq Z^{T_n}$. But then, by definition, $B \subseteq (Z^{T_n})^T$ which gives $B \subseteq Z^{T_{n+1}} \subseteq C(Z)$.

2. $C(Z)$ is the least model of T containing Z :

Let M be a model of T containing Z , i.e. $Z^{T_0} = Z \subseteq M$. Then $Z^T \subseteq M^T$ (just check definition of $(\dots)^T$). Evidently, $M = M^T$. Therefore, $Z^{T_1} = Z^T \subseteq M$. Applying this inductively gives $Z^{T_2} \subseteq M$, $Z^{T_3} \subseteq M$, \dots . Putting together yields

$C(Z) = \bigcup_{n=0}^{\infty} Z^{T_n} \subseteq M$. That is, $C(Z)$ is contained in every model M of T and is thus the least one. □

- Therefore, C is the closure operator which computes, given $Z \subseteq Y$, the least model of T containing Z .
- As argued in the proof, since Y is finite, $\bigcup_{n=0}^{\infty} Z^{T_n}$ “stops” after a finite number of steps. Namely, there is n_0 such that $Z^{T_n} = Z^{T_{n_0}}$ for $n > n_0$.
- The least such n_0 is the smallest n with $Z^{T_n} = Z^{T_{n+1}}$.
- Given T , $C(Z)$ can be computed: Use definition and stop whenever $Z^{T_n} = Z^{T_{n+1}}$. That is, put

$$C(Z) = Z \cup Z^{T_1} \cup Z^{T_2} \cup \dots \cup Z^{T_n}.$$
- There is a more efficient algorithm (called LinClosure) for computing $C(Z)$. See Maier D.: The Theory of Relational Databases. CS Press, 1983.

Example

Back to one of our previous examples: Let $Y = \{y_1, y_2, y_3\}$. Determine whether $T \models A \Rightarrow B$.

- $T = \{\{y_3\} \Rightarrow \{y_1, y_2\}, \{y_1, y_3\} \Rightarrow \{y_2\}\}$, $A \Rightarrow B$ is $\{y_2, y_3\} \Rightarrow \{y_1\}$.
 1. $\text{Mod}(T) = \{\emptyset, \{y_1\}, \{y_2\}, \{y_1, y_2\}, \{y_1, y_2, y_3\}\}$.
 2. By definition: $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\emptyset} = 1$, $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\{y_1\}} = 1$,
 $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\{y_2\}} = 1$, $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\{y_1, y_2\}} = 1$,
 $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\{y_1, y_2, y_3\}} = 1$.

Therefore, $T \models A \Rightarrow B$.

3. Now, using our theorem: The least model of T containing $A = \{y_2, y_3\}$ is $C_{\text{Mod}(T)}(A) = \{y_1, y_2, y_3\}$. Therefore, to verify $T \models A \Rightarrow B$, we just need to check whether $A \Rightarrow B$ is true in $\{y_1, y_2, y_3\}$. Since $\|\{y_2, y_3\} \Rightarrow \{y_1\}\|_{\{y_1, y_2, y_3\}} = 1$, we conclude $T \models A \Rightarrow B$.

Example (cntd.)

• $T = \{\{y_3\} \Rightarrow \{y_1, y_2\}, \{y_1, y_3\} \Rightarrow \{y_2\}\}$, $A \Rightarrow B$ is $\{y_2\} \Rightarrow \{y_1\}$.

1. $\text{Mod}(T) = \{\emptyset, \{y_1\}, \{y_2\}, \{y_1, y_2\}, \{y_1, y_2, y_3\}\}$.

2. By definition: $\|\{y_2\} \Rightarrow \{y_1\}\|_{\emptyset} = 1$, $\|\{y_2\} \Rightarrow \{y_1\}\|_{\{y_1\}} = 1$,

$\|\{y_2\} \Rightarrow \{y_1\}\|_{\{y_2\}} = 0$, we can stop.

Therefore, $T \not\models A \Rightarrow B$.

3. Now, using our theorem: The least model of T containing $A = \{y_2\}$ is

$C_{\text{Mod}(T)}(A) = \{y_2\}$. Therefore, to verify $T \models A \Rightarrow B$, we need to check whether $A \Rightarrow B$ is true in $\{y_2\}$. Since $\|\{y_2\} \Rightarrow \{y_1\}\|_{\{y_2\}} = 0$, we conclude $T \not\models A \Rightarrow B$.

Example

Let $Y = \{y_1, \dots, y_{10}\}$, $T = \{\{y_1, y_4\} \Rightarrow \{y_3\}, \{y_2, y_4\} \Rightarrow \{y_1\}, \{y_1, y_2\} \Rightarrow \{y_4, y_7\}, \{y_2, y_7\} \Rightarrow \{y_3\}, \{y_6\} \Rightarrow \{y_4\}, \{y_2, y_8\} \Rightarrow \{y_3\}, \{y_9\} \Rightarrow \{y_1, y_2, y_7\}\}$

1. Decide whether $T \models A \Rightarrow B$ for $A \Rightarrow B$ being $\{y_2, y_5, y_6\} \Rightarrow \{y_3, y_7\}$.

We need to check whether $\|A \Rightarrow B\|_{C_{\text{Mod}(T)}(A)} = 1$. First, we compute

$C_{\text{Mod}(T)}(A) = \bigcup_{n=0}^{\infty} A^{T_n}$. Recall:

$$A^{T_n} = A^{T_{n-1}} \cup \bigcup \{D \mid C \Rightarrow D \in T, C \subseteq A^{T_{n-1}}\}.$$

– $A^{T_0} = A = \{y_2, y_5, y_6\}$.

– $A^{T_1} = A^{T_0} \cup \bigcup \{\{y_4\}\} = \{y_2, y_4, y_5, y_6\}$.

Note: $\{y_4\}$ added because for $C \Rightarrow D$ being $\{y_6\} \Rightarrow \{y_4\}$ we have $\{y_6\} \subseteq A^{T_0}$.

– $A^{T_2} = A^{T_1} \cup \bigcup \{\{y_1\}, \{y_4\}\} = \{y_1, y_2, y_4, y_5, y_6\}$.

– $A^{T_3} = A^{T_2} \cup \bigcup \{\{y_3\}, \{y_1\}, \{y_4\}\} = \{y_1, y_2, y_3, y_4, y_5, y_6\}$.

– $A^{T_4} = A^{T_3} \cup \bigcup \{\{y_3\}, \{y_1\}, \{y_4, y_7\}, \{y_4\}\} = \{y_1, y_2, y_3, y_4, y_5, y_6, y_7\}$.

Example (cntd.)

$$- A^{T_5} = A^{T_4} \cup \bigcup \{ \{y_3\}, \{y_1\}, \{y_4, y_7\}, \{y_4\} \} = \{y_1, y_2, y_3, y_4, y_5, y_6, y_7\} = A^{T_4}, \text{ STOP.}$$

Therefore, $C_{\text{Mod}(T)}(A) = \{y_1, y_2, y_3, y_4, y_5, y_6, y_7\}$. Now, we need to check if

$\|A \Rightarrow B\|_{C_{\text{Mod}(T)}(A)} = 1$, i.e. if

$$\| \{y_2, y_5, y_6\} \Rightarrow \{y_3, y_7\} \|_{\{y_1, y_2, y_3, y_4, y_5, y_6, y_7\}} = 1.$$

Since this is true, we conclude $T \models A \Rightarrow B$.

2. Decide whether $T \models A \Rightarrow B$ for $A \Rightarrow B$ being $\{y_1, y_2, y_8\} \Rightarrow \{y_4, y_7\}$.

We need to check whether $\|A \Rightarrow B\|_{C_{\text{Mod}(T)}(A)} = 1$. First, we compute

$$C_{\text{Mod}(T)}(A) = \bigcup_{n=0}^{\infty} A^{T_n}.$$

$$- A^{T_0} = A = \{y_1, y_2, y_8\}.$$

$$- A^{T_1} = A^{T_0} \cup \bigcup \{ \{y_3\} \} = \{y_1, y_2, y_3, y_8\}.$$

$$- A^{T_2} = A^{T_1} \cup \bigcup \{ \{y_7\}, \{y_3\} \} = \{y_1, y_2, y_3, y_7, y_8\}.$$

$$- A^{T_3} = A^{T_2} \cup \bigcup \{ \{y_7\}, \{y_3\} \} = \{y_1, y_2, y_3, y_7, y_8\} = A^{T_2}, \text{ STOP.}$$

Thus, $C_{\text{Mod}(T)}(A) = \{y_1, y_2, y_3, y_7, y_8\}$. Now, we need to check if

$\|A \Rightarrow B\|_{C_{\text{Mod}(T)}(A)} = 1$, i.e. if $\| \{y_1, y_2, y_8\} \Rightarrow \{y_4, y_7\} \|_{\{y_1, y_2, y_3, y_7, y_8\}} = 1$. Since this is

not true, we conclude $T \not\models A \Rightarrow B$.

Further topics (future seminars)

- Bases of implications (how to obtain the least fully informative set of implications from data).
- Logic of implications (how to obtain a syntactico-semantically complete set of implications).
- Association rules and GUHA rules (how to obtain rules that allow exceptions, e.g. rules true in 90% cases).
- What can fuzzy logic add to such rules?

HOMEWORK/EASY (send solutions to radim.belohlavek@acm.org)

Let $Y = \{y_1, y_2, y_3\}$. Determine whether $T \models A \Rightarrow B$.

• $T_1 = \{\{y_3\} \Rightarrow \{y_1, y_2\}, \{y_1, y_3\} \Rightarrow \{y_2\}\}$.

$A \Rightarrow B: \{y_1, y_2\} \Rightarrow \{y_3\}, \emptyset \Rightarrow \{y_1\}$.

• $T_2 = \{\{y_3\} \Rightarrow \{y_1, y_2\}\}$.

$A \Rightarrow B: \{y_3\} \Rightarrow \{y_2\}, \{y_3, y_2\} \Rightarrow \emptyset$.

• $T_3 = \{\{y_1, y_3\} \Rightarrow \{y_2\}\}$.

$A \Rightarrow B: \{y_3\} \Rightarrow \{y_1, y_2\}, \Rightarrow \emptyset$.

• $T_4 = \{\{y_1\} \Rightarrow \{y_3\}, \{y_3\} \Rightarrow \{y_2\}, \}$.

$A \Rightarrow B: \{y_1\} \Rightarrow \{y_2\}, \{y_1\} \Rightarrow \{y_1, y_2, y_3\}$.

• $T_5 = \emptyset$.

$A \Rightarrow B: \{y_1\} \Rightarrow \{y_2\}, \{y_1\} \Rightarrow \{y_1, y_2, y_3\}$.

• $T_6 = \{\emptyset \Rightarrow \{y_1\}, \emptyset \Rightarrow \{y_3\}\}$.

$A \Rightarrow B: \{y_1\} \Rightarrow \{y_3\}, \emptyset \Rightarrow \{y_1, y_3\} \{y_1\} \Rightarrow \{y_2\}$.

• $T_7 = \{\{y_1\} \Rightarrow \emptyset, \{y_2\} \Rightarrow \emptyset, \{y_3\} \Rightarrow \emptyset\}$.

$A \Rightarrow B: \{y_1, y_2\} \Rightarrow \{y_3\}, \{y_1, y_2\} \Rightarrow \emptyset$.

• $T_8 = \{\{y_1\} \Rightarrow \{y_2\}, \{y_2\} \Rightarrow \{y_3\}, \{y_3\} \Rightarrow \{y_1\}\}$.

$A \Rightarrow B: \{y_1\} \Rightarrow \{y_3\}, \{y_1, y_3\} \Rightarrow \{y_2\}$.

HOMEWORK/MODERATE (send solutions to radim.belohlavek@acm.org)

1. Prove the following claim: Given a closure operator C in Y , $\mathcal{S}_C = \{A \in 2^X \mid A = C(A)\}$ is a closure system in Y .
2. Prove the following claim: Given a closure system in Y , putting

$$C_{\mathcal{S}}(A) = \bigcap \{B \in \mathcal{S} \mid A \subseteq B\}$$

for any $A \subseteq X$, $C_{\mathcal{S}}$ is a closure operator on Y .

3. Prove the following claim: The mappings defined in 1. and 2. are mutually inverse bijections between the set of all closure operators in Y and the set of all closure systems in Y .
4. Prove or disprove (by showing counterexamples) the following claims:
 - 4a. If $T_1 \subseteq T_2$ then $\text{Mod}(T_1) \supseteq \text{Mod}(T_2)$.
 - 4b. If $\text{Mod}(T_1) \supseteq \text{Mod}(T_2)$ then $T_1 \subseteq T_2$.
5. Let for a set $\mathcal{M} \subseteq 2^Y$ of sets of attributes denote by $\text{Fml}(\mathcal{M})$ the set of all attribute implications which are in every $M \in \mathcal{M}$. Prove that the pair $\langle \text{Mod}, \text{Fml} \rangle$ forms a Galois connection between the of all attribute implications over Y and the set of all subsets of Y .

HOMEWORK/HARD (send solutions to radim.belohlavek@acm.org)

1. If T is the set of all attribute implications valid in a formal context $\langle X, Y, I \rangle$, then $\text{Mod}(T) = \text{Int}(X, Y, I)$, i.e. models of T are just all the intents of the concept lattice $\mathcal{B}(X, Y, I)$.
2. Consider the problem of computing $C_{\text{Mod}(T)}(A)$ (output) from a set T of implications over Y and a subset A of Y (input). Consider the direct implementation of the algorithm for computing $C_{\text{Mod}(T)}$ given by the definition: compute $A^{T_1}, A^{T_2}, A^{T_n}$ until $A^{T_n} \neq A^{T_{n+1}}$ and output A^{T_n} , which is $C_{\text{Mod}(T)}(A)$. Prove that the worst case time complexity $t(n)$ of this algorithm is $\Theta(n^2)$, provided the input size is considered to be the number $n = |T|$ of implications in T . That is, show that $t(n) = O(n^2)$ and that $t(n) = \Omega(n)$.
Find an algorithm of worst case time complexity $\Theta(n)$.